

# Application of Graph Theory to Requirements Traceability

A methodology for visualization of large requirements sets

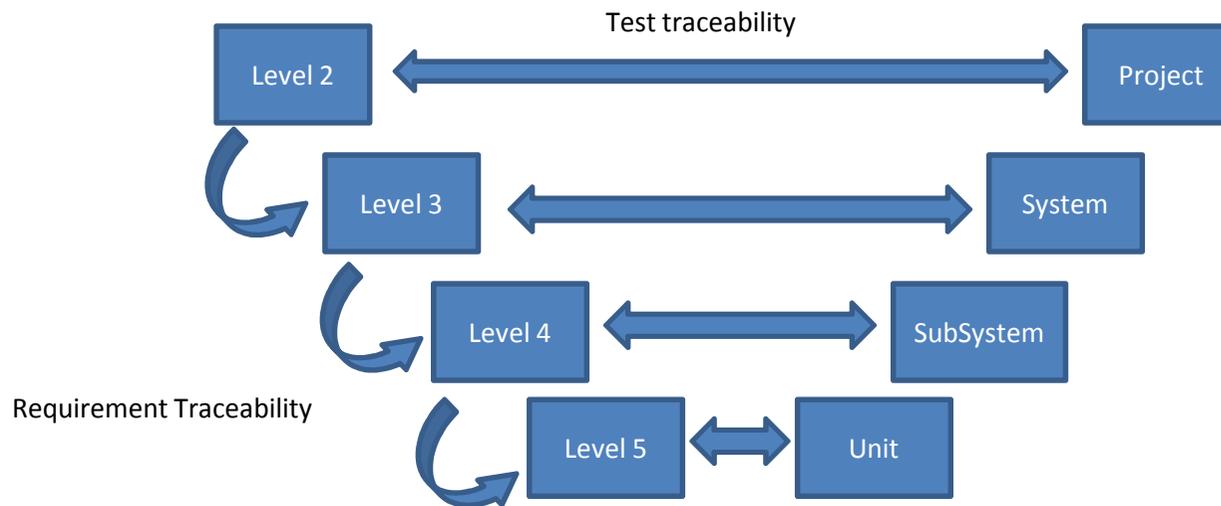
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L-3 Communications

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# Traceability in the Large

Requirements

Verification Events



Traceability is key to both requirements development and requirements verification  
Each project has unique approaches to traceability and verification

# Motivation for a Visualization Methodology

Studying characteristics of information flow in large Requirements sets

- >20 documents
- >10,000 requirements
- >7,000 linkages



LMA Requirement	FSW Requirement	TLCM Requirement
The flight system shall support the DOR tone capability in the SDST, including wideband DOR 387 tones at X-band.	The flight software shall command the transponder as defined by the transponder 1317 documentation	The flight software shall configure the transponder telemetry inputs in accordance with the active FS side whenever the transponder is powered ON. Reference transponder ICD for selection table. 706
The flight system shall accommodate PCM / PSK / PM modulation for the X band downlink. 1997		The flight software shall provide the capability to command an "active" telecom side which determines the "active" transponder in use and the uplink channel. 711
		The flight software shall propagate the power state and configuration of the transponder when changing the "active" telecom side. 712
		The flight software shall provide a default "active" telecom side upon initialization. The default "active" telecom side, in the absence of faults or obituary table entries, will be Side 1 (Telecom Side 1 uses SDST 1, and Telecom Side 2 uses SDST 2). 713
		The flight software shall only perform the necessary SDST initializations if a commanded "active" telecom side is different from the currently "active" telecom side. 714
		The flight software, upon initial application of transponder power ON, shall provide for a configurable default state. Subsequent power ON transitions will default to last commanded state. 725
		The flight software shall provide the capability to enable or disable the X-Band exciter for the active transponder. 1200
		The flight software shall provide the capability to enable or disable c mode for the active transponder. 1201
		The flight software shall provide the capability to enable or disable X-Band Ranging for the active transponder. 1202
		The flight software shall provide the capability to set the Ranging Modulation Index for the active transponder. 1203
		The flight software shall provide the capability to enable or disable X-Band Differential One-Way Ranging (DOR) Mode for the active transponder. 1204
		The flight software shall provide the capability to command an X-Band convolutional encoding mode of TLM_OFF, rate 7 1/2, or BYPASS for the active transponder. 1205
		The flight software shall provide the capability to to command the Ranging Mode to BASEBAND or EXTERNAL for the active transponder. 1206
		The flight software shall provide the capability to command the X-Band Subcarrier for the active transponder to one of the following frequencies: 281.25 Khz squarewave, 281.25 Khz sinewave, 25 Khz squarewave, or 25khz sinewave. 1207
		The flight software shall provide the capability to command the X-Band Squarewave Telemetry Modulation Index to one of 128 discrete values (0x00 to 0x7F) for the active transponder. 1208
		The flight software shall provide the capability to command the X-Band Sinewave Telemetry Modulation Index to one of 16 discrete values (0x0 to 0xF) for the active SDST. 1209
		The flight software shall provide the capability to command the X-Band telemetry modulation mode to SUBCARRIER or BPSK for the active transponder. 1211



Quickly communicate regarding patterns involving hundreds or thousands of requirements

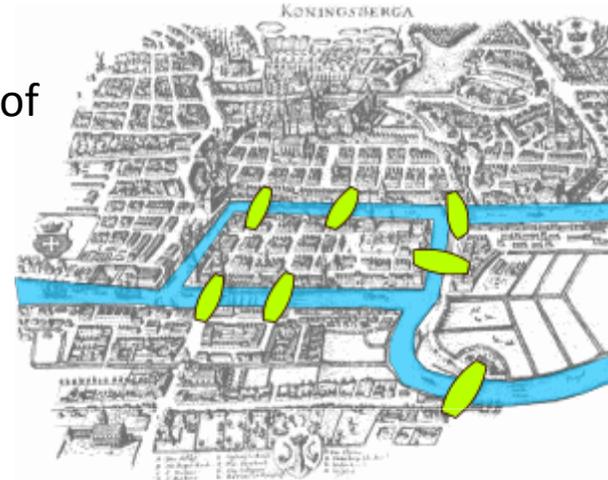
# Graph Theory History

Leonhard Euler: The seven bridges problem

Publication in 1736 as the first description of graph theory, and is generally regarded as the origin of topology

Vanermonde: The knights tour problem

Cauchy and L'Hullier: Relationships between faces, edges, and vertices of convex polyhedrons



Study of pair-wise relationships between objects

Graphs are the parent family to a variety of topologies:

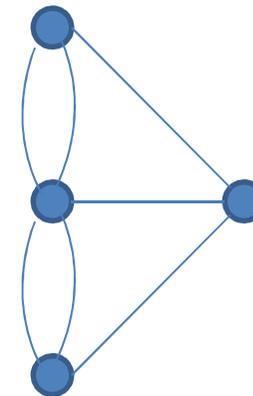
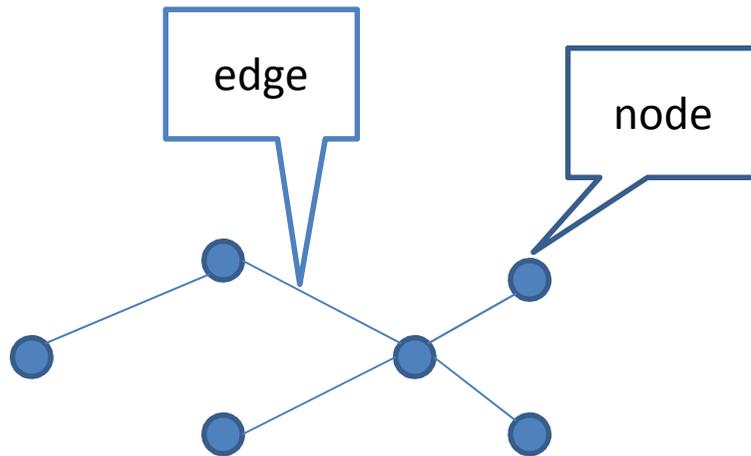
directed graphs

trees – Cayley and differential calculus

coloring problem

# What is a graph?

- Graph theory is the study of mathematical structures used to model relationships between objects in finite collections.
- A graph is composed of nodes and edges
- Graphs can be classified as undirected, directed, tree, planar, etc depending upon the nature of the connections.

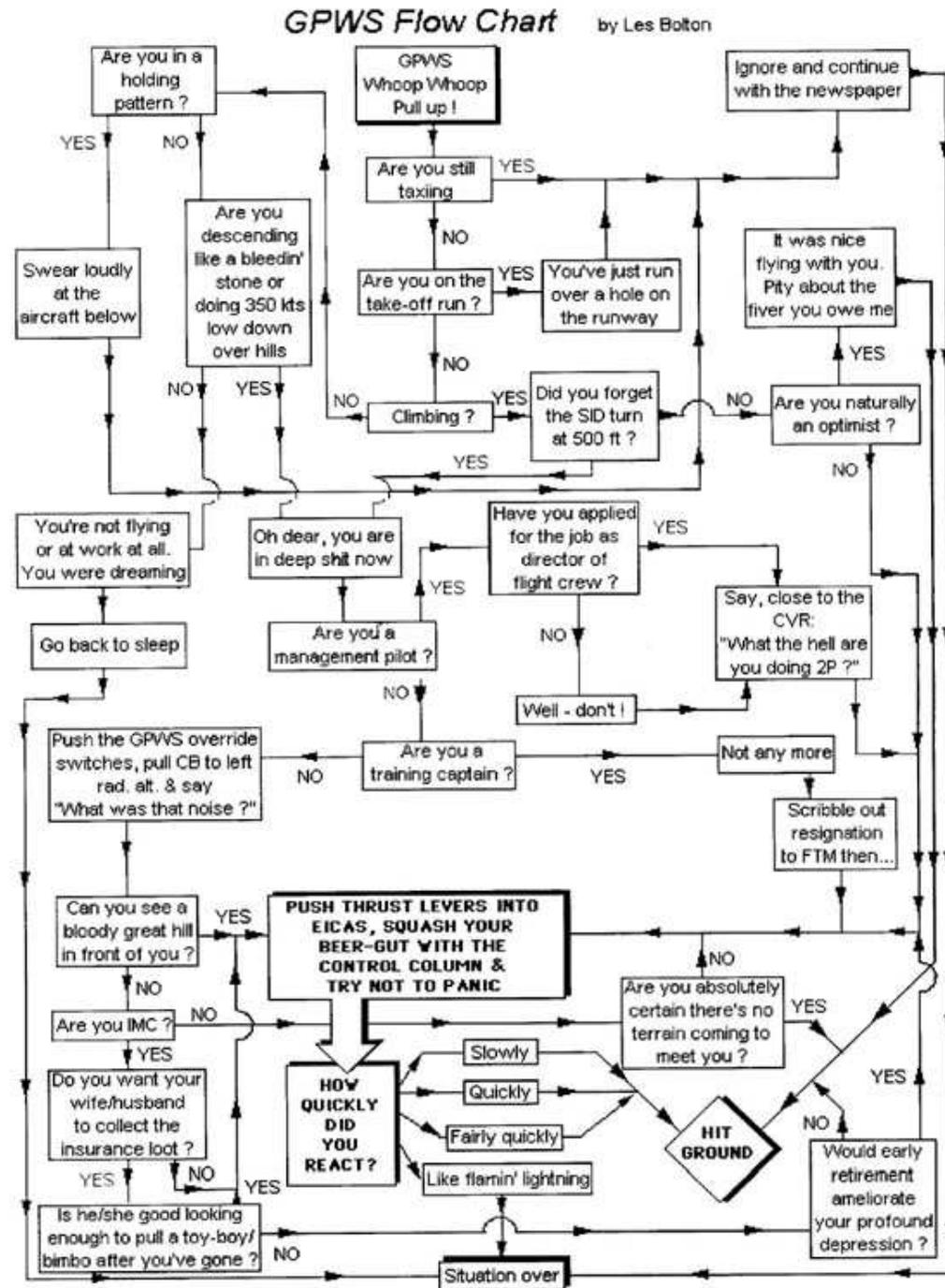


The Seven Bridges Problem  
Four nodes, seven edges

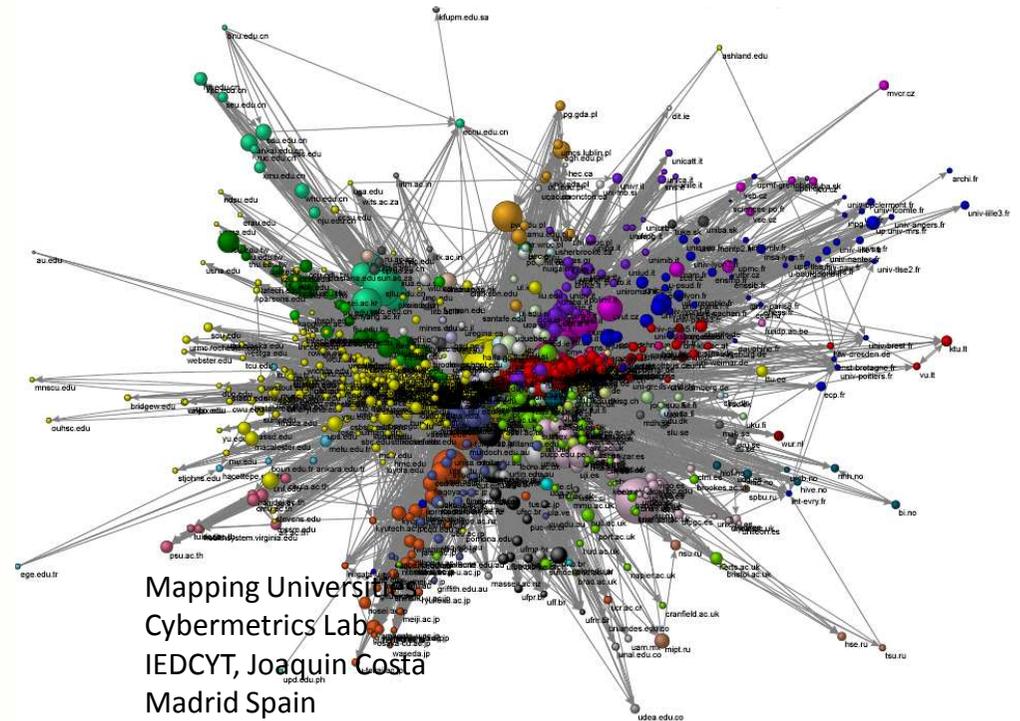
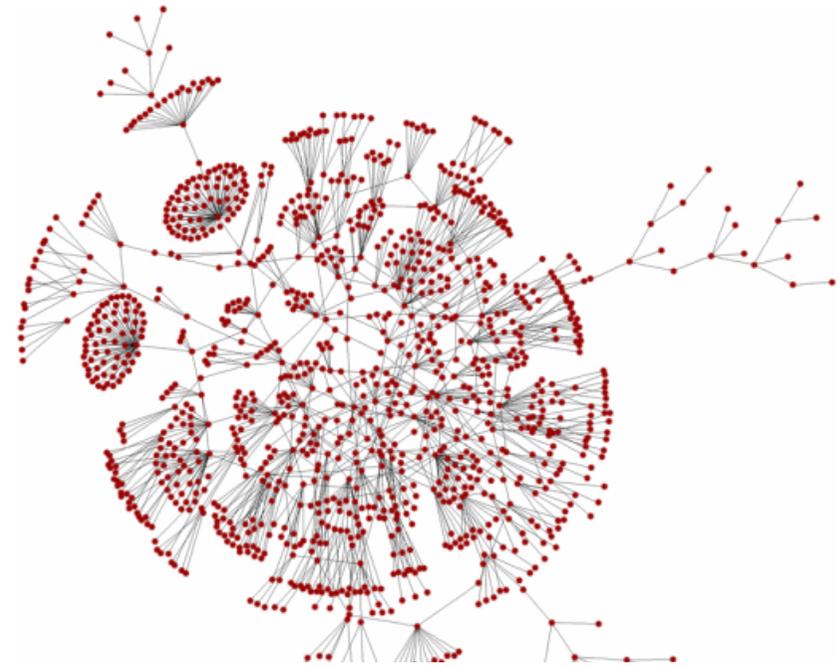
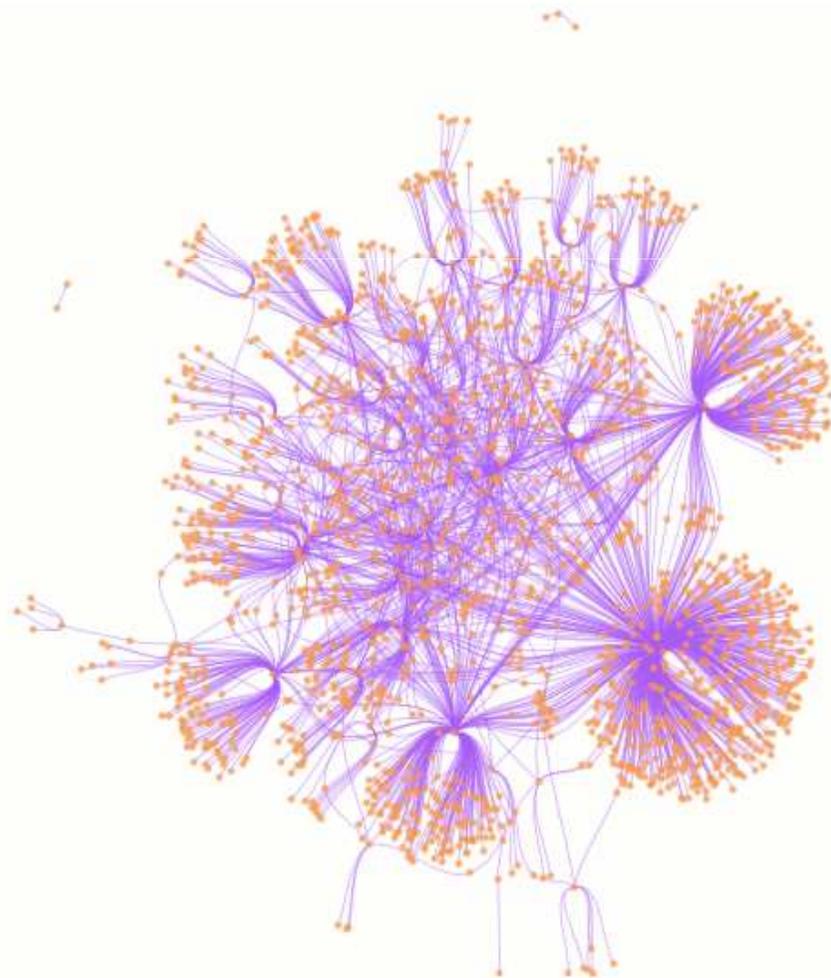


# Flow Charts as Graphs

Directed graph  
Sometimes cyclic



# Network Exploration Graphs



Mapping University  
Cybermetrics Lab  
IEDCYT, Joaquin Costa  
Madrid Spain

# Graphs of Requirements Sets

Getting to the good stuff soon now...

## Types of Graphs

Simple graph – nodes and edges

Directed graph – nodes and edges with direction (digraph)

Acyclic graph – no cycles (loops)

Connected graph – every node is reachable from any other node

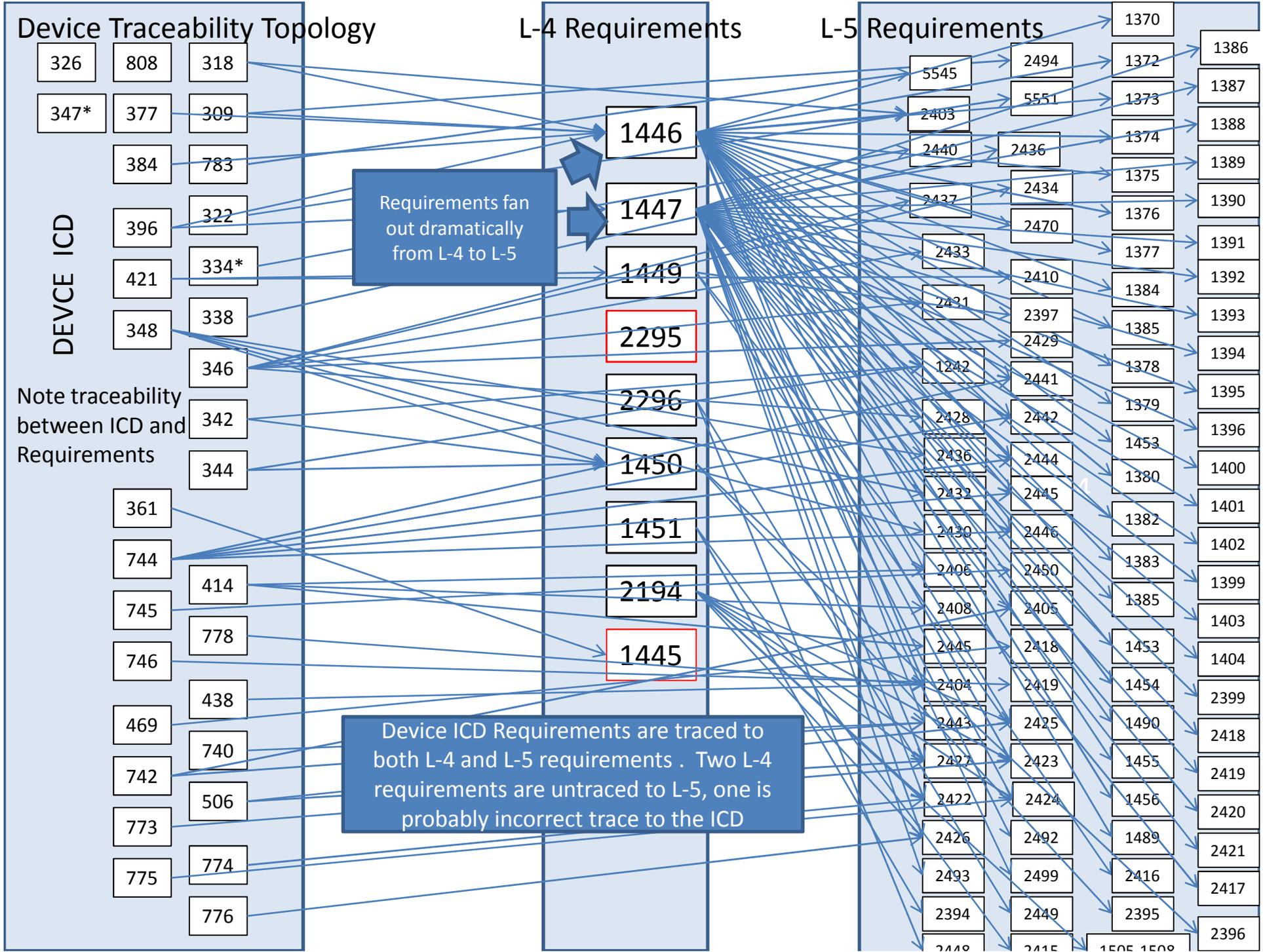
Tree – connected acyclic graph

Forest – acyclic graph but unconnected

In the general case, requirements traceability forms an acyclic digraph, or forest

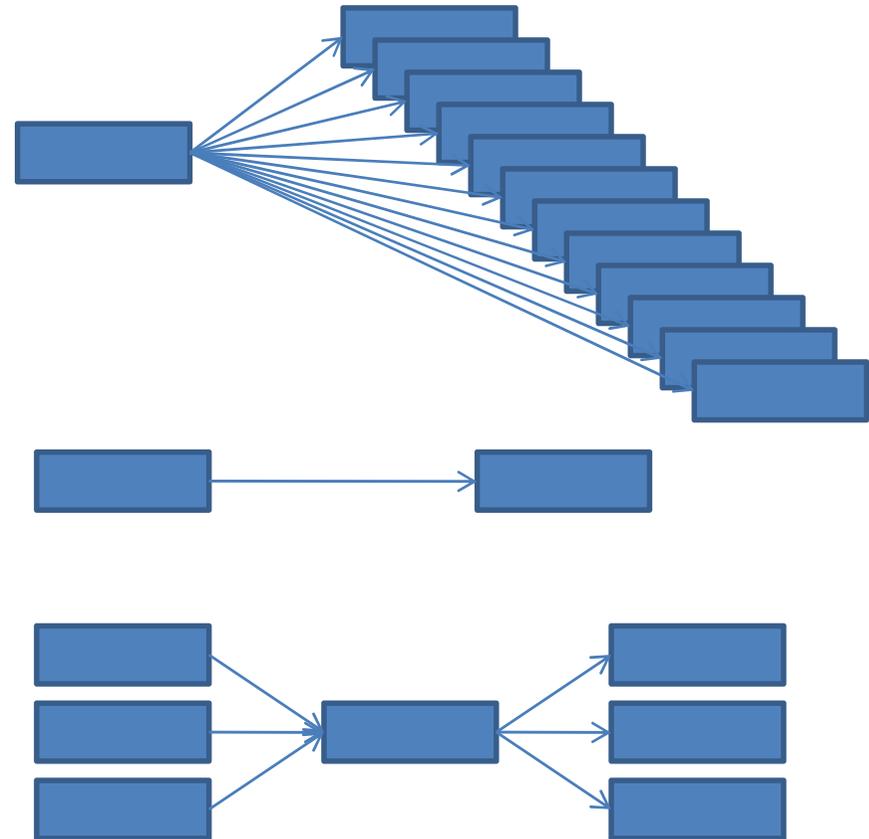
- Generally no single top-level node
- Generally not connected
- Almost always acyclic
- Directed

In the following examples of real system requirements graphs, the graphs are drawn as digraphs with the arrow pointing from the parent to the child. Untraced requirements are shown with red borders. We use boxes to denote the nodes simply because they fit the numbers better. These examples show a subnet of the full requirements net for clarity.

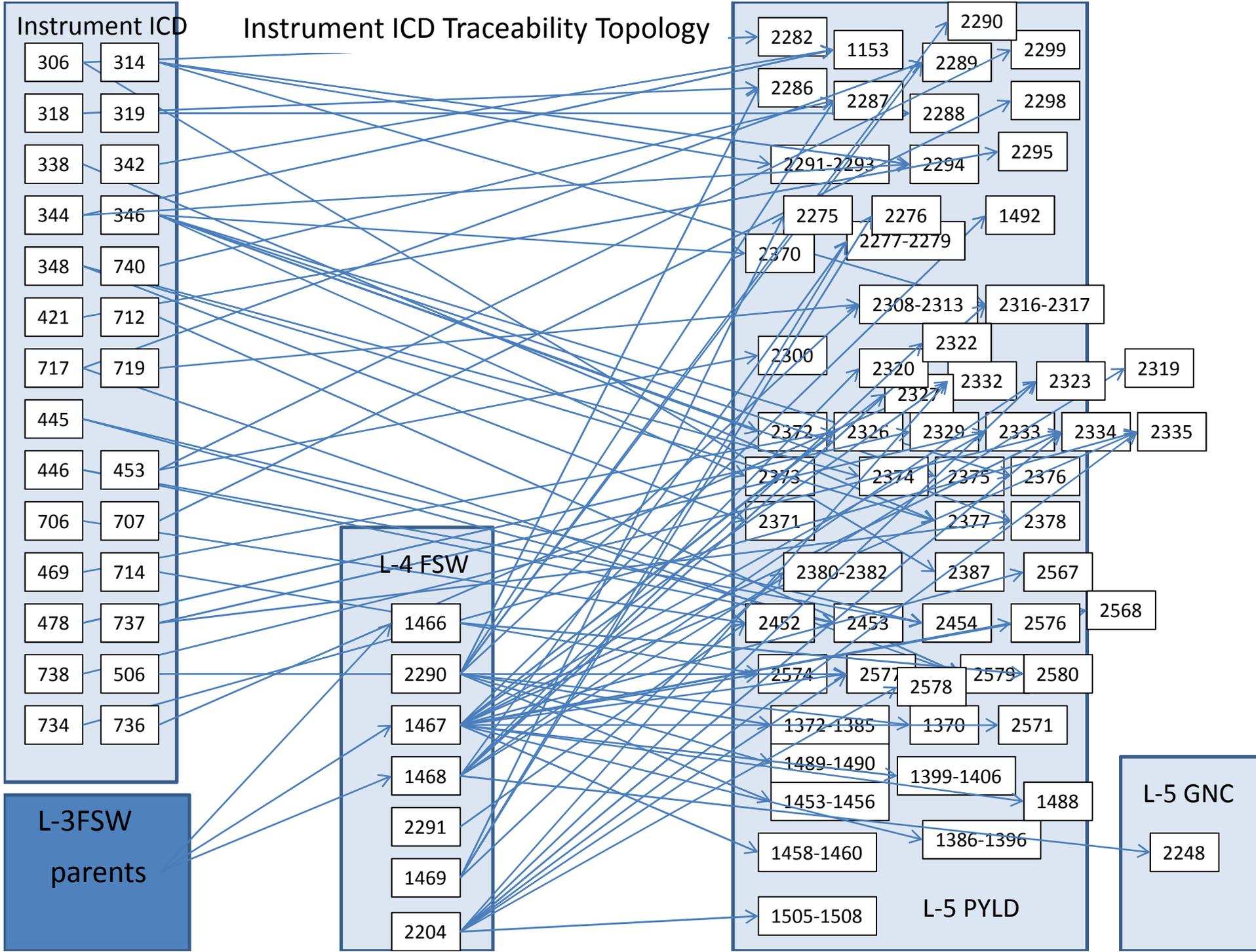


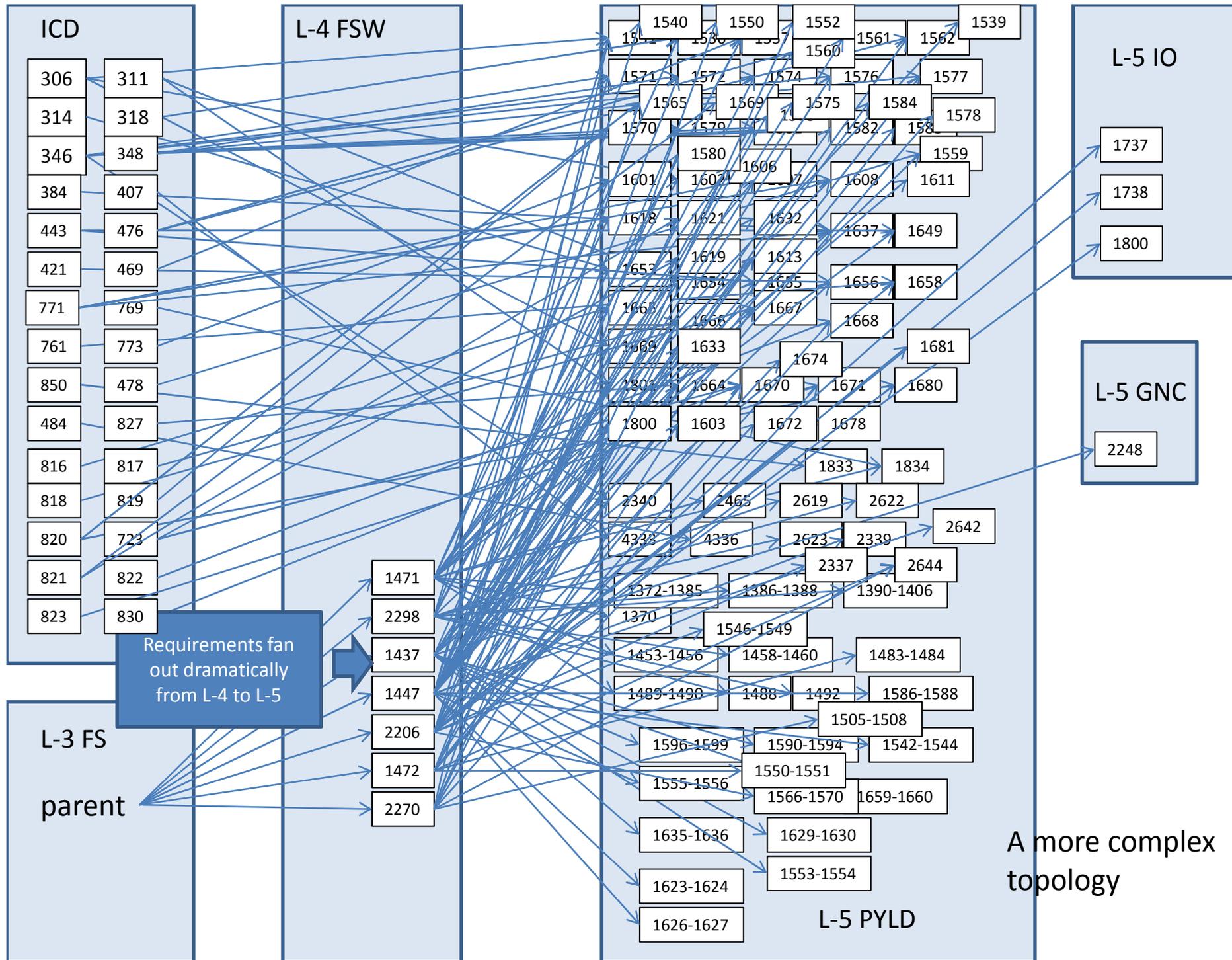
# Traceability Patterns

- Large fan-out from parent to child suggest a large change in level of abstraction.
- One-to-one suggests under-specified lower-level requirements.
- Hour-glass traces seem to indicate serious problems in the intermediate requirements document; traceability event-horizon. May indicate verification difficulties.

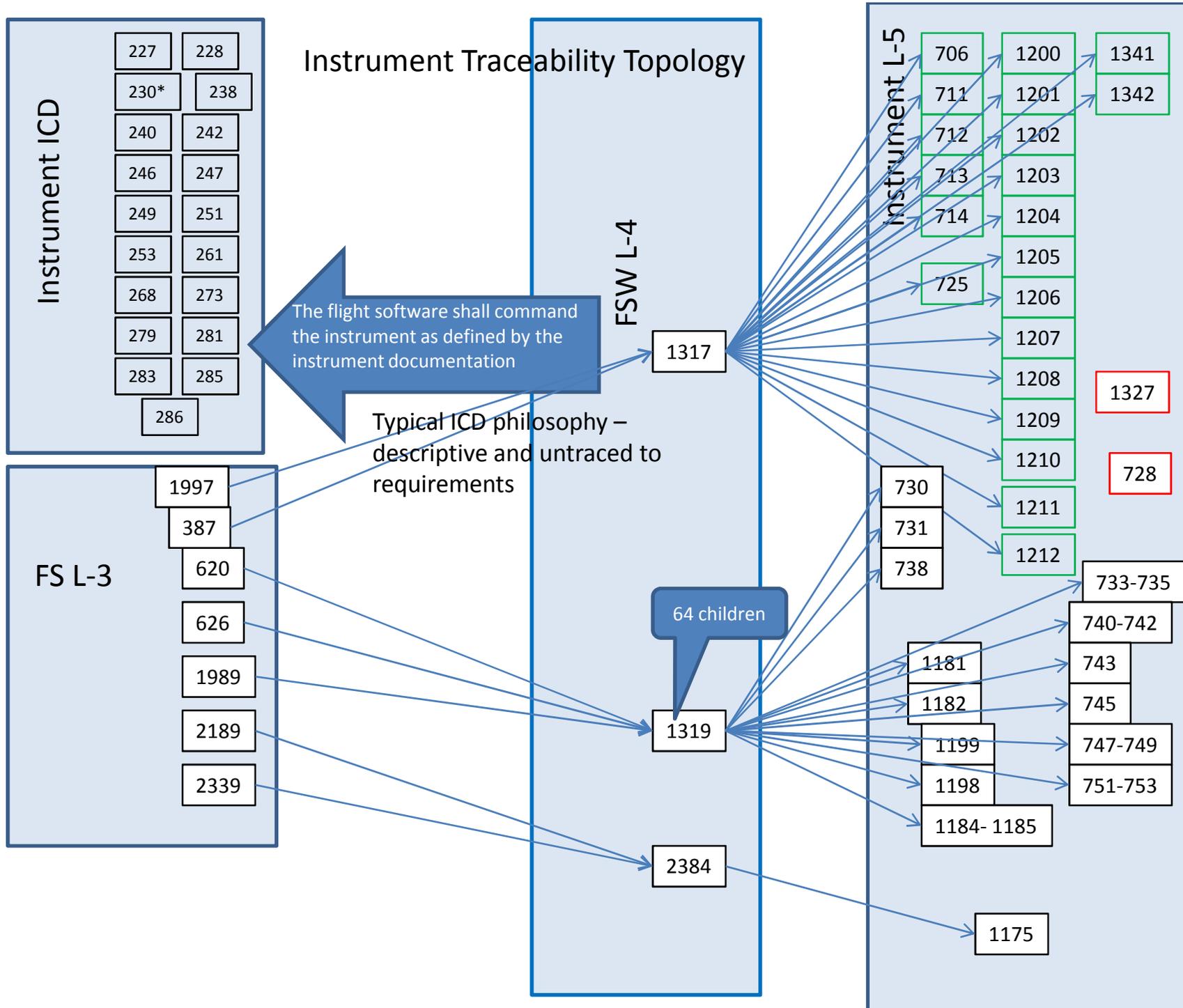


# Instrument ICD Traceability Topology





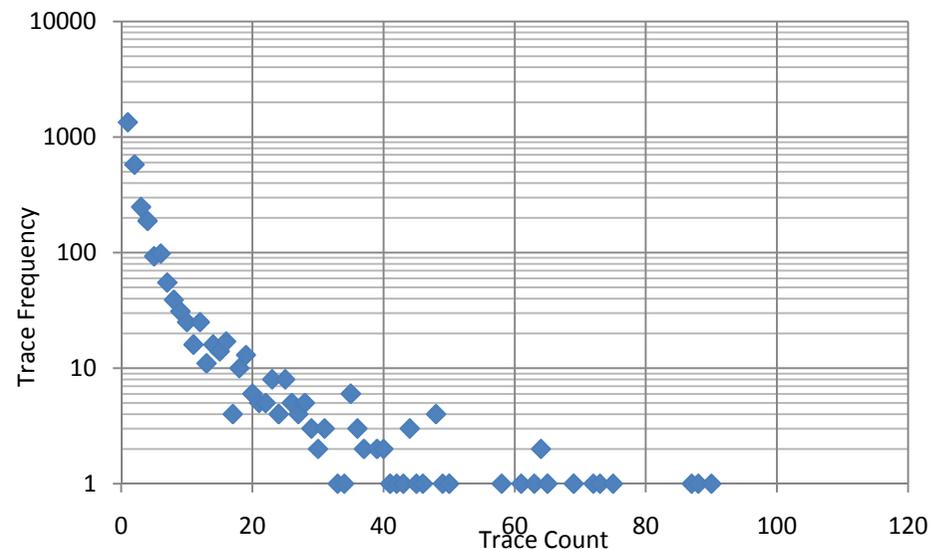
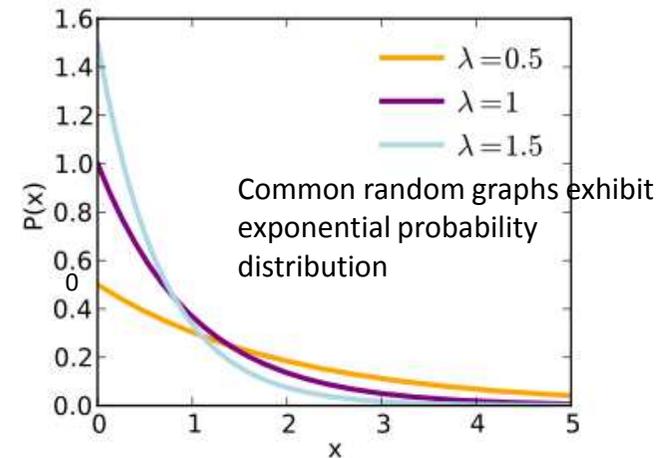
# Instrument Traceability Topology



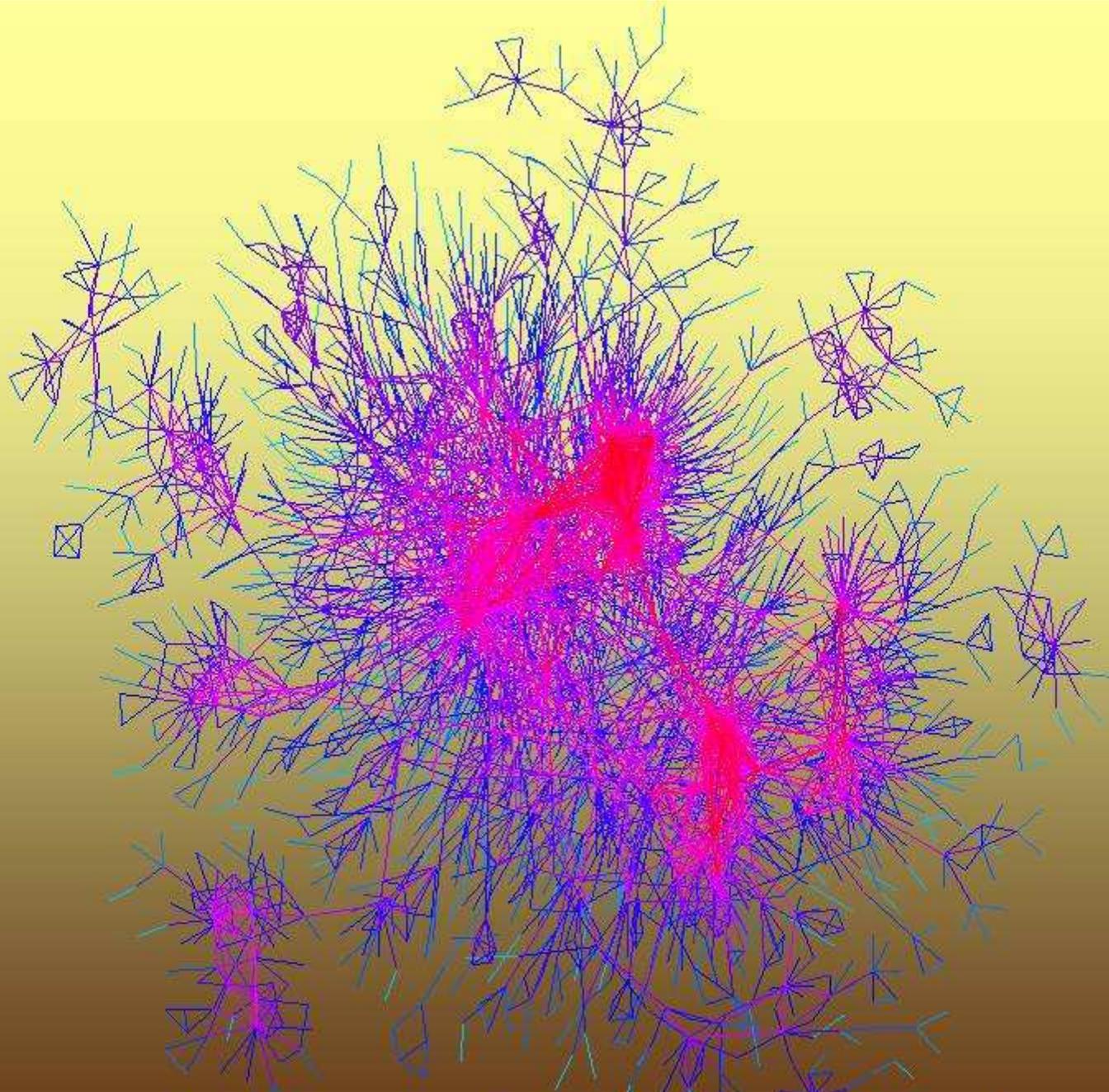
# Graphs as Traceability Diagnostics

- Histograms of connection counts:
  - Statistics of connection counts may suggest decomposition problems
  - Distributions are typically exponential (Internet, Kevin Bacon – movie graph)

Conjecture: Exponent may be relatable to the overall degree of abstraction change between linked requirements:  
High values mean small change



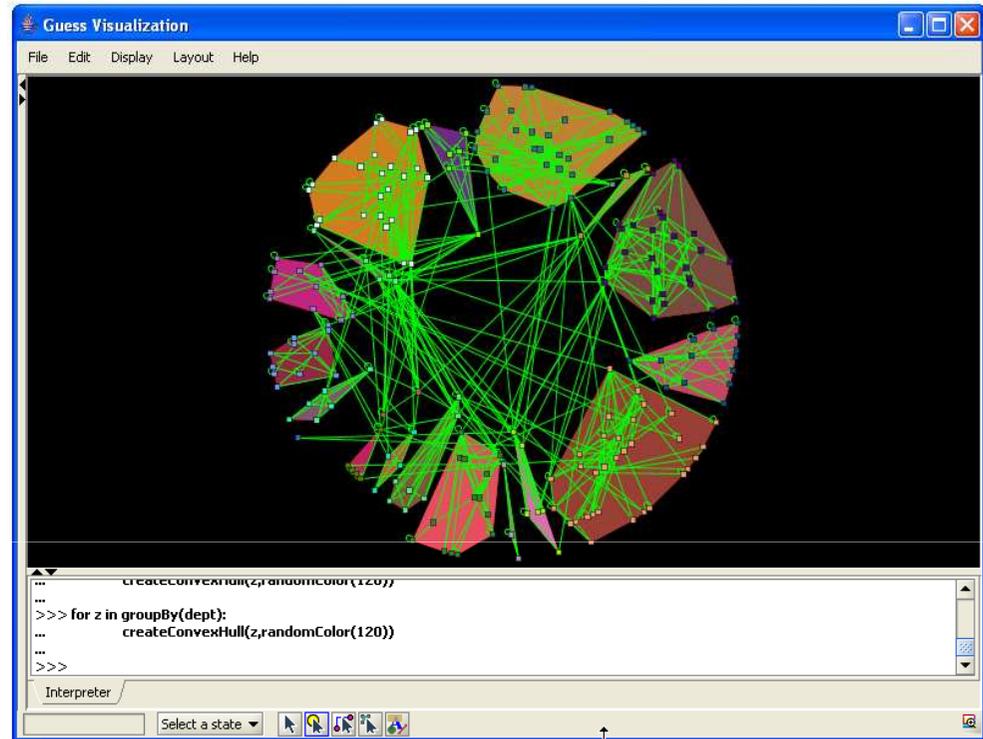
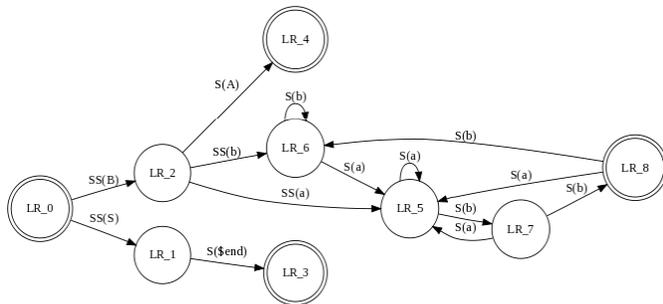
Example real project connection histogram



A subgraph of the Hollywood graph.

# Automation of the Graphing Process

PowerPoint is NOT the best tool for analysis

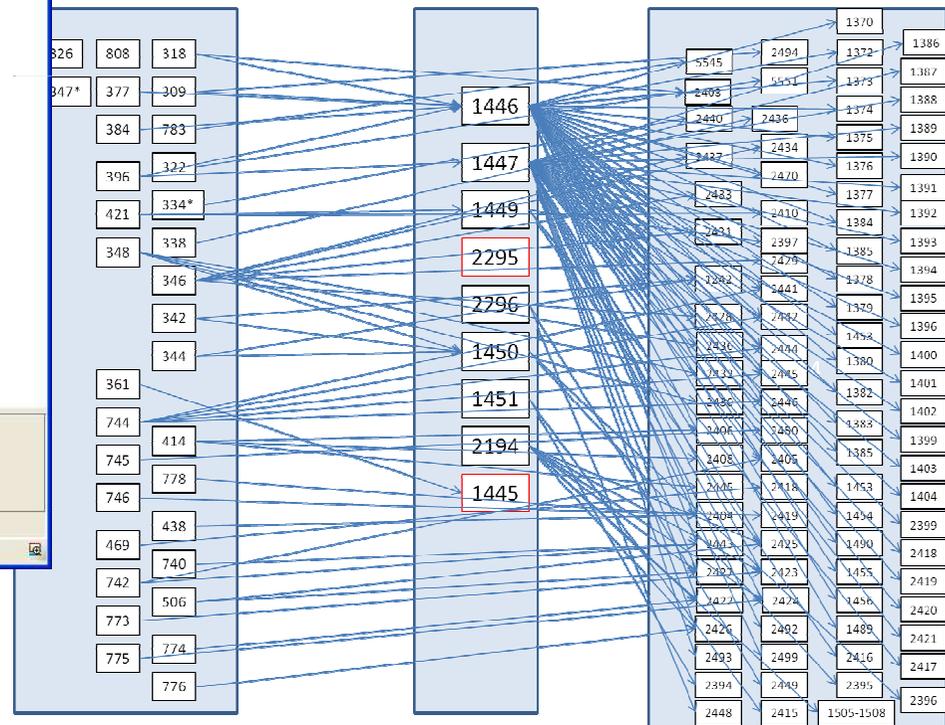
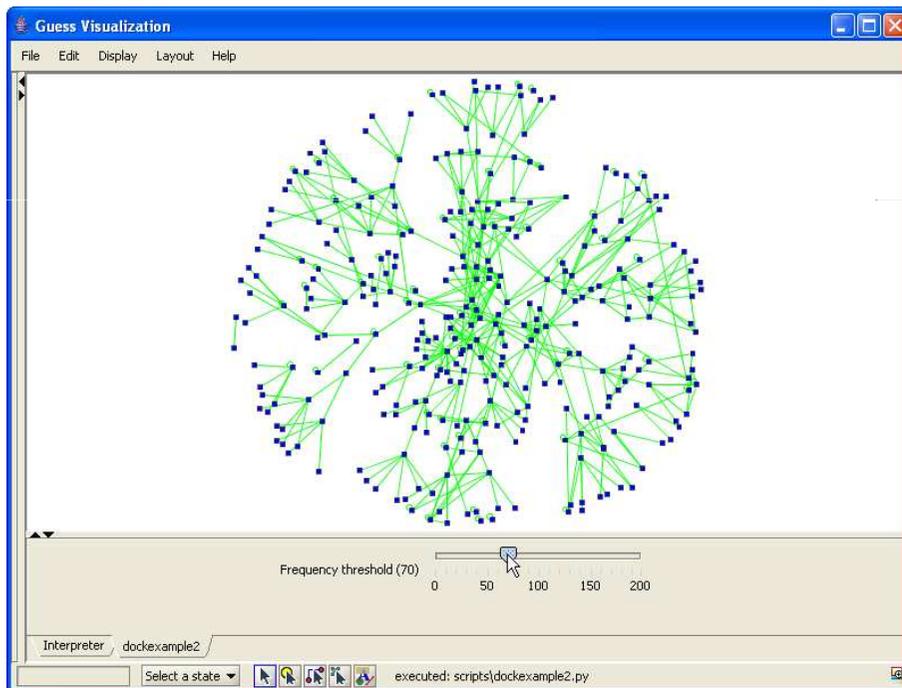


Automatic graph generation from A matrix and specification of groups  
Numerous applications available

- VCG - <http://rw4.cs.uni-sb.de/~sander/html/gsvcg1.html>
- Graphviz <http://www.graphviz.org/>
- Jgraph - [www.jgraph.com](http://www.jgraph.com)
- Guess - <http://graphexploration.cond.org/>

# How Connected is a Graph?

Separability of subnets -> modularity of requirements to limit propagation of change



# Expressing Graphs as Mathematical Structures - Vocabulary

Vertex: Endpoint (or connection point or node)

Edge: Connection between vertices

Incidence List : Array of pairs (tuples if directed) of vertices or connections

Adjacency List: List of pairs of vertices as a list (2x n array)

Incidence Matrix: Vertices by Edges matrix where each entry contains the endpoint data (1 = incident, 0 = not incident)

Adjacency matrix (A): N by N matrix where N = the number of vertices in the graph. Entries are either 0 if not connected, 1 if connected.

If there is an edge from vertex k to vertex j then  $A(j,k)=1$

Degree: Matrix of connection counts on the diagonal (D)

Laplacian matrix:  $L=D-A$ , where D= the diagonal degree matrix



**Danger: Math Ahead**

# Connectivity and Graphing

Here comes the math

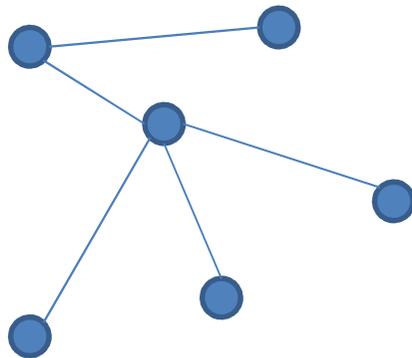
Graph	Fiedler Value
Path	$1/n^{**2}$
Grid	$1/n$
3D Grid	$n^{**2}/3$
Expander	1
Binary tree	$1/n$
dumbell	$1/n$

The smallest nonzero eigenvalue of the Laplacian matrix is called the Fiedler value (or spectral gap).

Small values of the Fiedler number mean the graph is easier to cut into two subnets. If the number is large, then every cut of the graph must cut many edges.

Conjecture: Would a large Fiedler number for a requirements graph indicate a system that was difficult to partition into subnets, thus difficult to change?

# A Simple Graph and Spectral Analysis



A Matrix

0	1				
1	0	1			
	1	0	1	1	1
		1	0		
		1		0	
		1			0

Laplacian (D-A)

1	-1				
-1	2	-1			
	-1	4	-1	-1	-1
		-1	1		
		-1		1	
		-1			1



Eigenvalue:

From linear algebra

$Lx = \lambda x$  where  $\lambda$  is an eigenvalue

And  $x$  is a non-null eigenvector

Because  $L$  is symmetric the

eigenvalues are all real

$$\lambda = \{0, 0.486, 1, 1, 2.428, 5.086\}$$

Fiedler number = 0.486

implying somewhere between an  
expander (1) and a tree form (1/6)

# Summary

- Graphs can be useful visualization tools for large requirements sets
  - Big picture viewpoint
  - Patterns easily recognized
  - Multi-level tracing
  - Identification of subnets
- Potential for analysis
  - Relationship between connection histogram and requirement decomposition
  - Ability to quantify interconnectedness by spectral analysis